

Simplified Implementation of the MAP Decoder

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Introduction : MAP Decoder

▶ $\hat{u}_k = \arg \max_{i \in \{0,1\}} \Pr[u_k = i | \underline{R}_1^N]$

▶ LAPPR

$$\Lambda_k = \log \frac{\Pr[u_k = 1 | \underline{R}_1^N]}{\Pr[u_k = 0 | \underline{R}_1^N]} = \log \frac{\Pr[u_k = 1, \underline{R}_1^N]}{\Pr[u_k = 0, \underline{R}_1^N]}.$$

▶ MAP Rule:

$$\hat{u}_k = \begin{cases} 1, & \Lambda_k \geq 0 \\ 0, & \text{otherwise} \end{cases}.$$

BCJR Algorithm [2], [3]

$$\Lambda_k = \log \frac{\sum_{m' \in S} \sum_{m \in S} \alpha_{k-1}(m') \gamma_k^1(m', m) \beta_k(m)}{\sum_{m' \in S} \sum_{m \in S} \alpha_{k-1}(m') \gamma_k^0(m', m) \beta_k(m)}$$

S = set of states of trellis

S_k = state of the trellis after k^{th} input.

$$\alpha_k(m) = \Pr[S_k = m, \underline{R}_1^k]$$

$$\beta_k(m) = \Pr[\underline{R}_{k+1}^N | S_k = m]$$

$$\gamma_k^i(m', m) = \Pr[u_k = i, S_k = m, \underline{R}_k | S_{k-1} = m']$$

BCJR Algorithm : Forward and backward recursions

$$\blacktriangleright \alpha_k(m) = \sum_{m' \in S} \sum_{i=0}^1 \alpha_{k-1}(m') \gamma_k^i(m', m)$$

$$\blacktriangleright \beta_k(m) = \sum_{m' \in S} \sum_{i=0}^1 \beta_{k+1}(m') \gamma_{k+1}^i(m, m')$$

$$\blacktriangleright \gamma_k^i(m', m) = \Pr[u_k = i] \Pr[S_k = m | S_{k-1} = m', u_k = i] \Pr[\underline{R}_k | S_{k-1} = m', u_k = i, S_k = m]$$

BCJR Algorithm : Computation and Memory Requirements

- ▶ $\mathcal{O}(|S|^2)$ multiplications and additions for computing the metrics for each k
- ▶ $\mathcal{O}(|S|^2)$ multiplications and additions for computing the LAPPR for each k
- ▶ Need to store forward metric for every k

Problematic for large block-length and codes with higher memory

A New 'Maximum' Function

- ▶ $\max^*(x, y) \triangleq \log(e^x + e^y) = \max(x, y) + \log(1 + e^{-|y-x|})$
- ▶ Key insight : \max^* can be approximated by \max
- ▶ $\max^*(x, y, z) \triangleq \max^*(\max^*(x, y), z) = \log(e^x + e^y + e^z)$

And so on...

BCJR Algorithm : Simplification of Computation [1]

- ▶ $\tilde{a}_k(m) \triangleq \log \alpha_k(m)$
 $\tilde{b}_k(m) \triangleq \log \beta_k(m)$
 $\tilde{c}_{i,k}(m', m) \triangleq \log \gamma_k^i(m', m)$

$$\Lambda_k \approx \max_{m, m' \in \mathcal{S}} [\tilde{a}_{k-1}(m') + \tilde{c}_{1,k}(m', m) + \tilde{b}_k(m)] -$$
$$\max_{m, m' \in \mathcal{S}} [\tilde{a}_{k-1}(m') + \tilde{c}_{0,k}(m', m) + \tilde{b}_k(m)]$$

$$\tilde{a}_k(m) \approx \max_{m' \in \mathcal{S}, i \in \{0,1\}} [\tilde{a}_{k-1}(m') + \tilde{c}_{i,k}(m', m)]$$

$$\tilde{b}_j(m) \approx \max_{m' \in \mathcal{S}, i \in \{0,1\}} [\tilde{b}_{j+1}(m') + \tilde{c}_{i,j+1}(m', m)]$$

BCJR Algorithm : Simplification of Computation

$$\begin{aligned}\tilde{c}_{i,k}(m', m) &= \log \Pr[u_k = i] + \\ &\log \Pr[S_k = m | S_{k-1} = m', u_k = i] + \\ &\log \Pr[\underline{R}_k | S_{k-1} = m', u_k = i, S_k = m]\end{aligned}$$

► Initializations

$$\tilde{a}_0(m) = \begin{cases} 0, & m = s_0 \\ -\infty, & \text{otherwise.} \end{cases}$$

$$\tilde{b}_N(m) = \begin{cases} 0, & m = s_N \\ -\infty, & \text{otherwise.} \end{cases}$$

BCJR Algorithm : Simplification of Computation

- ▶ Forward and backward metrics can be computed similarly to VA
- ▶ Problem of normalization at each step solved

Memory requirement problems

BCJR Algorithm : Reducing Memory Requirements [1]

- ▶ Status till now :

Forward metric stored for all stages till N

Backward metric stored for one stage at a time for 'dual-maxima' process

Decoded vector output only after time N (after the whole input is seen)

- ▶ Larger block-length increases memory requirement

BCJR Algorithm : Reducing Memory Requirements

- ▶ Key idea : Behavior of VA nearly independent of initial conditions beyond a few constraint lengths
- ▶ Use two backward decoders in tandem
- ▶ $L =$ 'learning period'

Received symbols delayed by $2L$

BCJR Algorithm : Reducing Memory Requirements

- ▶ Forward decoder starts at branch 0 at time $2L$
- ▶ Forward decoder stores every branch metric for each time
- ▶ Time $2L$: first backward decoder starts backwards from branch $2L$ and stores only the most recent metric till branch L
- ▶ Time $3L$: first backward decoder meets the computed forward metric at branch L

BCJR Algorithm : Reducing Memory Requirements

- ▶ Time $3L$ to time $4L$: first backward decoder moves till branch 0 and dual maxima processor outputs soft decisions for first L branches
- ▶ Time $3L$: second backward decoder starts backwards from branch $3L$ and stores only the most recent metric till branch $2L$
- ▶ Time $4L$: second backward decoder meets the computed forward metric at branch $2L$

BCJR Algorithm : Reducing Memory Requirements

- ▶ Time $4L$ to time $5L$: second backward decoder moves till branch L and dual maxima processor outputs soft decisions for branches L through $2L$
- ▶ Two backward processors hop forward $4L$ branches every time $2L$ sets of backward state metrics have been generated
- ▶ Time-sharing of dual-maxima processor

BCJR Algorithm : Reducing Memory Requirements

- ▶ State metrics for only $2L$ branches stored by first decoder
- ▶ Soft decisions for first $2L$ branches generated at time $5L$
- ▶ Four times the complexity of a simple VA for the same convolutional code

Schematic Representation

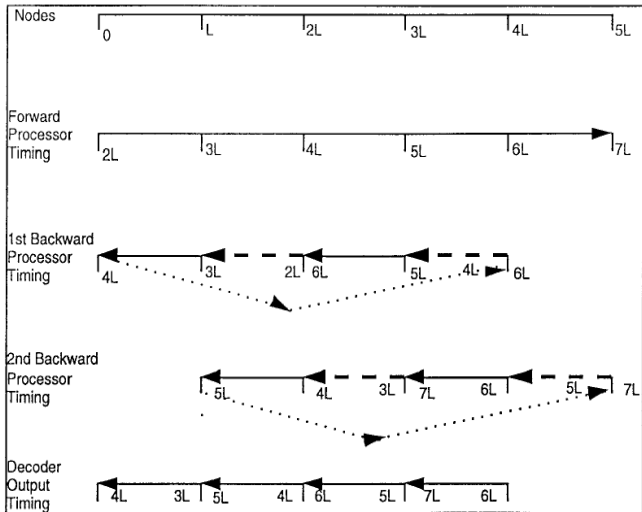
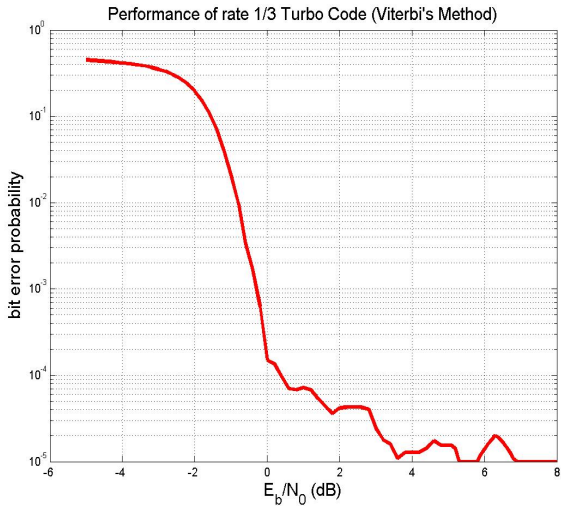




Figure: Scheduling [1]

Results


Block length 10,000



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